

# Nominal Life

An LM Guide in motion under an external load receives repeated stress on its raceways and rolling elements. When the stress reaches the limit, the surface of the raceways and rolling elements flake in places due to rolling fatigue. This phenomenon is called flaking. The service life of an LM Guide is the total travel distance until the first flaking occurs on any of the raceways or the rolling elements as a result of rolling fatigue of the material.

The nominal life defined below is typically used as a guideline for obtaining the service life of the LM Guide.

The nominal life means the total travel distance that 90% of a group of units of the same LM Guide model can achieve without flaking after individually running under the same conditions.

## Calculating the Nominal Life

The nominal life ( $L_{10}$ ) of an LM Guide is obtained from the following formula using the basic dynamic load rating (C), which is based on a reference distance of 50 km for an LM Guide with balls and 100 km for an LM Guide with rollers, and the calculated load acting on the LM Guide ( $P_c$ ).

- LM Guide with balls (using a basic dynamic load rating based on a nominal life of 50 km)

$$L_{10} = \left( \frac{C}{P_c} \right)^3 \times 50 \dots\dots\dots (1)$$

$L_{10}$	: Nominal life	(km)
C	: Basic dynamic load rating	(N)
$P_c$	: Calculated load	(N)

- LM Guide with rollers (using a basic dynamic load rating based on a nominal life of 100 km)

$$L_{10} = \left( \frac{C}{P_c} \right)^{\frac{10}{3}} \times 100 \dots\dots\dots (2)$$

Note: These nominal life formulas may not apply if the length of the stroke is less than or equal to twice the length of the LM block.

When comparing the nominal life ( $L_{10}$ ), you must take into account whether the basic dynamic load rating was defined based on 50 km or 100 km. Convert the basic dynamic load rating based on ISO 14728-1 as necessary.

ISO-regulated basic dynamic load rating conversion formulas:

- LM Guide with balls

$$C_{100} = \frac{C_{50}}{1.26}$$

$C_{50}$  : Basic dynamic load rating based on a nominal life of 50 km

$C_{100}$  : Basic dynamic load rating based on a nominal life of 100 km

- LM Guide with rollers

$$C_{100} = \frac{C_{50}}{1.23}$$

## Calculating the Modified Nominal Life

During use, an LM Guide may be subjected to vibrations and shocks as well as fluctuating loads, which are difficult to detect. In addition, the surface hardness of the raceways, the operating temperature, and having LM blocks arranged directly behind one another will have a decisive impact on the service life. Taking these factors into account, the modified nominal life ( $L_{10m}$ ) can be calculated according to the following formulas (3) and (4).

• Modified factor  $\alpha$

$$\alpha = \frac{f_H \cdot f_T \cdot f_C}{f_W}$$

- $\alpha$  : Modified factor  
 $f_H$  : Hardness factor (see Fig. 10 on **B1-75**)  
 $f_T$  : Temperature factor (see Fig. 11 on **B1-75**)  
 $f_C$  : Contact factor (see Table 3 on **B1-75**)  
 $f_W$  : Load factor (see Table 4 on **B1-76**)

• Modified nominal life  $L_{10m}$

• LM Guide with balls

$$L_{10m} = \left( \alpha \times \frac{C}{P_C} \right)^3 \times 50 \dots\dots\dots (3)$$

- $L_{10m}$  : Modified nominal life (km)  
 $C$  : Basic dynamic load rating (N)  
 $P_C$  : Calculated load (N)

• LM Guide with rollers

$$L_{10m} = \left( \alpha \times \frac{C}{P_C} \right)^{\frac{10}{3}} \times 100 \dots\dots\dots (4)$$

Once the nominal life ( $L_{10}$ ) has been obtained, the service life time can be obtained using the following equation if the stroke length and the number of reciprocations are constant.

$$L_h = \frac{L_{10} \times 10^6}{2 \times \ell_s \times n_1 \times 60}$$

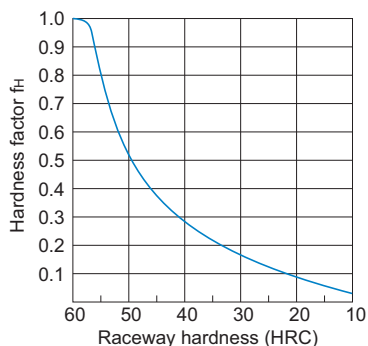
- $L_h$  : Service life time (h)  
 $\ell_s$  : Stroke length (mm)  
 $n_1$  : Number of reciprocations per minute ( $\text{min}^{-1}$ )

**$f_H$ : Hardness Factor**

To ensure that the LM Guide achieves optimum load capacity, the raceway hardness must be between 58 and 64 HRC.

If the hardness is lower than this range, the basic dynamic load rating and the basic static load rating decrease. Therefore, it is necessary to multiply each rating by the respective hardness factor ( $f_H$ ).

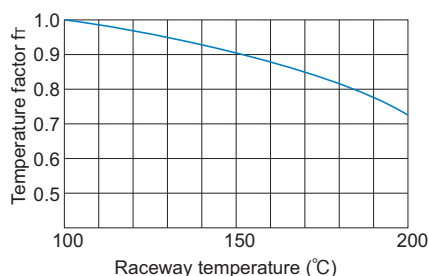
Since the LM Guide has sufficient hardness, the  $f_H$  value for the LM Guide is normally 1.0 unless otherwise specified.

Fig. 10: Hardness Factor ( $f_H$ ) **$f_T$ : Temperature Factor**

If the temperature of the operating environment surrounding the LM Guide exceeds 100°C, take into account the adverse effect of the high temperature and multiply the basic load ratings by the temperature factor indicated in Fig. 11.

In addition, the selected LM Guide must also be of a high-temperature type.

Note: An LM Guide not designed to withstand high temperatures should be used at 80°C or less. Please contact THK if application requirements exceed 80°C.

Fig. 11: Temperature Factor ( $f_T$ ) **$f_C$ : Contact Factor**

When multiple LM blocks are used in close contact with each other, it is difficult to achieve uniform load distribution due to moment loads and mounting-surface accuracy. When using multiple blocks in close contact with each other, multiply the basic load rating ( $C$  or  $C_0$ ) by the corresponding contact factor indicated in Table 3.

Note: If uneven load distribution is expected in a large machine, take into account the respective contact factor indicated in Table 3.

Table 3: Contact Factor ( $f_C$ )

Number of blocks used in close contact	Contact factor $f_C$
2	0.81
3	0.72
4	0.66
5	0.61
6 or greater	0.6
Normal use	1

### **$f_w$ : Load Factor**

In general, reciprocating machines tend to involve vibrations or impacts during operation. It is extremely difficult to accurately determine vibrations generated during high-speed operation and impacts that occur during frequent starts and stops. Therefore, where the effects of speed and vibration are estimated to be significant, divide the basic dynamic load rating (C) by a load factor selected from Table 4, which contains empirically obtained data.

Table 4: Load Factor ( $f_w$ )

Vibrations/ impacts	Speed (V)	$f_w$
Faint	Very low $V \leq 0.25$ m/s	1 to 1.2
Weak	Low $0.25 \text{ m/s} < V \leq 1$ m/s	1.2 to 1.5
Medium	Medium $1 \text{ m/s} < V \leq 2$ m/s	1.5 to 2
Strong	High $V > 2$ m/s	2 to 3.5

## Example of Calculating the Nominal Life (1) - with Horizontal Mount and High-Speed Acceleration

Conditions

Model No. : HSR35L

(basic dynamic load rating:  $C = 65.0 \text{ kN}$ )

(basic static load rating:  $C_0 = 91.7 \text{ kN}$ )

Mass :  $m_1 = 800 \text{ kg}$  Distance:  $\ell_0 = 600 \text{ mm}$

$m_2 = 500 \text{ kg}$   $\ell_1 = 400 \text{ mm}$

Speed :  $V = 0.5 \text{ m/s}$   $\ell_2 = 120 \text{ mm}$

Time :  $t_1 = 0.05 \text{ s}$   $\ell_3 = 50 \text{ mm}$

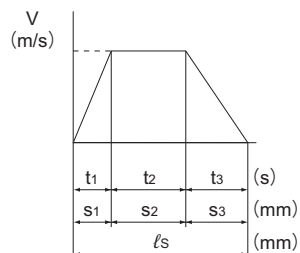
$t_2 = 2.8 \text{ s}$   $\ell_4 = 200 \text{ mm}$

$t_3 = 0.15 \text{ s}$   $\ell_5 = 350 \text{ mm}$

Acceleration :  $\alpha_1 = 10 \text{ m/s}^2$

$\alpha_3 = 3.333 \text{ m/s}^2$

Stroke :  $\ell_s = 1450 \text{ mm}$



Gravitational acceleration  $g = 9.8 \text{ (m/s}^2\text{)}$

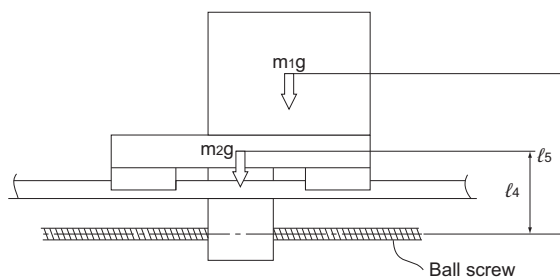
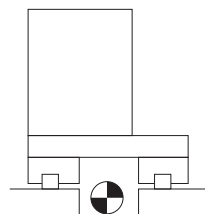
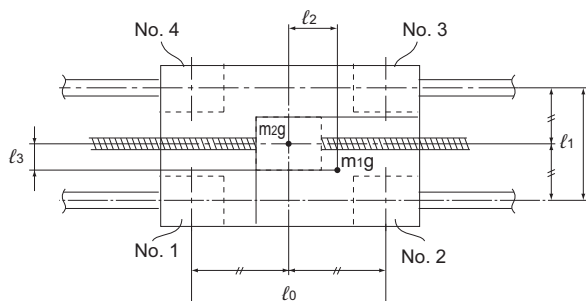


Fig. 12: Operating Conditions

### Load Applied to the LM Block

Calculate the load applied to each LM block.

#### ● During uniform motion

##### ■ Applied load in the radial direction $P_n$

$$P_1 = + \frac{m_1 g}{4} - \frac{m_1 g \cdot \ell_2}{2 \cdot \ell_0} + \frac{m_1 g \cdot \ell_3}{2 \cdot \ell_1} + \frac{m_2 g}{4} = +2891 \text{ N}$$

$$P_2 = + \frac{m_1 g}{4} + \frac{m_1 g \cdot \ell_2}{2 \cdot \ell_0} + \frac{m_1 g \cdot \ell_3}{2 \cdot \ell_1} + \frac{m_2 g}{4} = +4459 \text{ N}$$

$$P_3 = + \frac{m_1 g}{4} + \frac{m_1 g \cdot \ell_2}{2 \cdot \ell_0} - \frac{m_1 g \cdot \ell_3}{2 \cdot \ell_1} + \frac{m_2 g}{4} = +3479 \text{ N}$$

$$P_4 = + \frac{m_1 g}{4} - \frac{m_1 g \cdot \ell_2}{2 \cdot \ell_0} - \frac{m_1 g \cdot \ell_3}{2 \cdot \ell_1} + \frac{m_2 g}{4} = +1911 \text{ N}$$

#### ● During leftward acceleration

##### ■ Applied load in the radial direction $P^l a_n$

$$P^l a_1 = P_1 - \frac{m_1 \cdot \alpha_1 \cdot \ell_5}{2 \cdot \ell_0} - \frac{m_2 \cdot \alpha_1 \cdot \ell_4}{2 \cdot \ell_0} = - 275.6 \text{ N}$$

$$P^l a_2 = P_2 + \frac{m_1 \cdot \alpha_1 \cdot \ell_5}{2 \cdot \ell_0} + \frac{m_2 \cdot \alpha_1 \cdot \ell_4}{2 \cdot \ell_0} = + 7625.6 \text{ N}$$

$$P^l a_3 = P_3 + \frac{m_1 \cdot \alpha_1 \cdot \ell_5}{2 \cdot \ell_0} + \frac{m_2 \cdot \alpha_1 \cdot \ell_4}{2 \cdot \ell_0} = + 6645.6 \text{ N}$$

$$P^l a_4 = P_4 - \frac{m_1 \cdot \alpha_1 \cdot \ell_5}{2 \cdot \ell_0} - \frac{m_2 \cdot \alpha_1 \cdot \ell_4}{2 \cdot \ell_0} = - 1255.6 \text{ N}$$

##### ■ Applied load in the lateral direction $P^l a_n$

$$P^l a_1 = - \frac{m_1 \cdot \alpha_1 \cdot \ell_3}{2 \cdot \ell_0} = - 333.3 \text{ N}$$

$$P^l a_2 = + \frac{m_1 \cdot \alpha_1 \cdot \ell_3}{2 \cdot \ell_0} = + 333.3 \text{ N}$$

$$P^l a_3 = + \frac{m_1 \cdot \alpha_1 \cdot \ell_3}{2 \cdot \ell_0} = + 333.3 \text{ N}$$

$$P^l a_4 = - \frac{m_1 \cdot \alpha_1 \cdot \ell_3}{2 \cdot \ell_0} = - 333.3 \text{ N}$$

#### ● During leftward deceleration

##### ■ Applied load in the radial direction $P^l d_n$

$$P^l d_1 = P_1 + \frac{m_1 \cdot \alpha_3 \cdot \ell_5}{2 \cdot \ell_0} + \frac{m_2 \cdot \alpha_3 \cdot \ell_4}{2 \cdot \ell_0} = + 3946.6 \text{ N}$$

$$P^l d_2 = P_2 - \frac{m_1 \cdot \alpha_3 \cdot \ell_5}{2 \cdot \ell_0} - \frac{m_2 \cdot \alpha_3 \cdot \ell_4}{2 \cdot \ell_0} = + 3403.4 \text{ N}$$

$$P^l d_3 = P_3 - \frac{m_1 \cdot \alpha_3 \cdot \ell_5}{2 \cdot \ell_0} - \frac{m_2 \cdot \alpha_3 \cdot \ell_4}{2 \cdot \ell_0} = + 2423.4 \text{ N}$$

$$P^l d_4 = P_4 + \frac{m_1 \cdot \alpha_3 \cdot \ell_5}{2 \cdot \ell_0} + \frac{m_2 \cdot \alpha_3 \cdot \ell_4}{2 \cdot \ell_0} = + 2966.6 \text{ N}$$

### ■ Applied load in the lateral direction $P_{tld_n}$

$$P_{tld_1} = + \frac{m_1 \cdot \alpha_3 \cdot \ell_3}{2 \cdot \ell_0} = + 111.1 \text{ N}$$

$$P_{tld_2} = - \frac{m_1 \cdot \alpha_3 \cdot \ell_3}{2 \cdot \ell_0} = - 111.1 \text{ N}$$

$$P_{tld_3} = - \frac{m_1 \cdot \alpha_3 \cdot \ell_3}{2 \cdot \ell_0} = - 111.1 \text{ N}$$

$$P_{tld_4} = + \frac{m_1 \cdot \alpha_3 \cdot \ell_3}{2 \cdot \ell_0} = + 111.1 \text{ N}$$

### ● During rightward acceleration

#### ■ Applied load in the radial direction $P_{ra_n}$

$$P_{ra_1} = P_1 + \frac{m_1 \cdot \alpha_1 \cdot \ell_5}{2 \cdot \ell_0} + \frac{m_2 \cdot \alpha_1 \cdot \ell_4}{2 \cdot \ell_0} = + 6057.6 \text{ N}$$

$$P_{ra_2} = P_2 - \frac{m_1 \cdot \alpha_1 \cdot \ell_5}{2 \cdot \ell_0} - \frac{m_2 \cdot \alpha_1 \cdot \ell_4}{2 \cdot \ell_0} = + 1292.4 \text{ N}$$

$$P_{ra_3} = P_3 - \frac{m_1 \cdot \alpha_1 \cdot \ell_5}{2 \cdot \ell_0} - \frac{m_2 \cdot \alpha_1 \cdot \ell_4}{2 \cdot \ell_0} = + 312.4 \text{ N}$$

$$P_{ra_4} = P_4 + \frac{m_1 \cdot \alpha_1 \cdot \ell_5}{2 \cdot \ell_0} + \frac{m_2 \cdot \alpha_1 \cdot \ell_4}{2 \cdot \ell_0} = + 5077.6 \text{ N}$$

### ■ Applied load in the lateral direction $P_{tra_n}$

$$P_{tra_1} = + \frac{m_1 \cdot \alpha_1 \cdot \ell_3}{2 \cdot \ell_0} = + 333.3 \text{ N}$$

$$P_{tra_2} = - \frac{m_1 \cdot \alpha_1 \cdot \ell_3}{2 \cdot \ell_0} = - 333.3 \text{ N}$$

$$P_{tra_3} = - \frac{m_1 \cdot \alpha_1 \cdot \ell_3}{2 \cdot \ell_0} = - 333.3 \text{ N}$$

$$P_{tra_4} = + \frac{m_1 \cdot \alpha_1 \cdot \ell_3}{2 \cdot \ell_0} = + 333.3 \text{ N}$$

### ● During rightward deceleration

#### ■ Applied load in the radial direction $P_{rd_n}$

$$P_{rd_1} = P_1 - \frac{m_1 \cdot \alpha_3 \cdot \ell_5}{2 \cdot \ell_0} - \frac{m_2 \cdot \alpha_3 \cdot \ell_4}{2 \cdot \ell_0} = + 1835.4 \text{ N}$$

$$P_{rd_2} = P_2 + \frac{m_1 \cdot \alpha_3 \cdot \ell_5}{2 \cdot \ell_0} + \frac{m_2 \cdot \alpha_3 \cdot \ell_4}{2 \cdot \ell_0} = + 5514.6 \text{ N}$$

$$P_{rd_3} = P_3 + \frac{m_1 \cdot \alpha_3 \cdot \ell_5}{2 \cdot \ell_0} + \frac{m_2 \cdot \alpha_3 \cdot \ell_4}{2 \cdot \ell_0} = + 4534.6 \text{ N}$$

$$P_{rd_4} = P_4 - \frac{m_1 \cdot \alpha_3 \cdot \ell_5}{2 \cdot \ell_0} - \frac{m_2 \cdot \alpha_3 \cdot \ell_4}{2 \cdot \ell_0} = + 855.4 \text{ N}$$

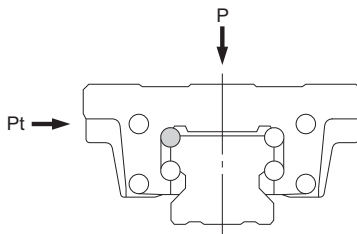
### ■ Applied load in the lateral direction Ptrd.

$$Ptrd_1 = - \frac{m_1 \cdot \alpha_3 \cdot \ell_3}{2 \cdot \ell_0} = -111.1 \text{ N}$$

$$Ptrd_2 = + \frac{m_1 \cdot \alpha_3 \cdot \ell_3}{2 \cdot \ell_0} = +111.1 \text{ N}$$

$$Ptrd_3 = + \frac{m_1 \cdot \alpha_3 \cdot \ell_3}{2 \cdot \ell_0} = +111.1 \text{ N}$$

$$Ptrd_4 = - \frac{m_1 \cdot \alpha_3 \cdot \ell_3}{2 \cdot \ell_0} = -111.1 \text{ N}$$



### Combined Radial and Thrust Load

The combined radial and thrust load is calculated for each block only on the groove where the load is greatest.

Under these operating conditions, for each block, the groove for which the load is greatest is groove 1.<sup>1</sup> Because groove 1 bears  $P^2 > 0$  and  $Pt > 0$  loads, it is 0 N when  $P < 0$  and  $Pt < 0$  loads are applied.

When calculating for the groove that will bear  $P < 0$  and  $Pt < 0$  loads, use the absolute value of the load.

<sup>1</sup> The reason that groove 1 has the greatest load is that mass  $m_1$  is applied unevenly to the table and is not distributed equally to all grooves in the block.

<sup>2</sup>  $P$  refers to the radial load that each groove bears.

#### ● During uniform motion

$$P_{E1} = P_1 = 2891 \text{ N}$$

$$P_{E2} = P_2 = 4459 \text{ N}$$

$$P_{E3} = P_3 = 3479 \text{ N}$$

$$P_{E4} = P_4 = 1911 \text{ N}$$

#### ● During leftward acceleration

$$P_{E1a1} = |Pl_{a1}| + |Pt_{l_{a1}}| = 0 \text{ N}$$

$$P_{E1a2} = |Pl_{a2}| + |Pt_{l_{a2}}| = 7958.9 \text{ N}$$

$$P_{E1a3} = |Pl_{a3}| + |Pt_{l_{a3}}| = 6978.9 \text{ N}$$

$$P_{E1a4} = |Pl_{a4}| + |Pt_{l_{a4}}| = 0 \text{ N}$$

$$Pl_{a1}, Pt_{l_{a1}}, Pl_{a4}, \text{ and } Pt_{l_{a4}} = 0 \text{ N}$$

#### ● During leftward deceleration

$$P_{E1d1} = |Pl_{d1}| + |Pt_{l_{d1}}| = 4057.7 \text{ N}$$

$$P_{E1d2} = |Pl_{d2}| + |Pt_{l_{d2}}| = 3403.4 \text{ N}$$

$$P_{E1d3} = |Pl_{d3}| + |Pt_{l_{d3}}| = 2423.4 \text{ N}$$

$$P_{E1d4} = |Pl_{d4}| + |Pt_{l_{d4}}| = 3077.7 \text{ N}$$

$$Pt_{l_{d2}} \text{ and } Pt_{l_{d3}} = 0 \text{ N}$$

#### ● During rightward acceleration

$$P_{E1a1} = |Pra_1| + |Ptr_{a1}| = 6390.9 \text{ N}$$

$$P_{E1a2} = |Pra_2| + |Ptr_{a2}| = 1292.4 \text{ N}$$

$$P_{E1a3} = |Pra_3| + |Ptr_{a3}| = 312.4 \text{ N}$$

$$P_{E1a4} = |Pra_4| + |Ptr_{a4}| = 5410.9 \text{ N}$$

$$Ptr_{a2} \text{ and } Ptr_{a3} = 0 \text{ N}$$

#### ● During rightward deceleration

$$P_{E1d1} = |Pr_{d1}| + |Ptr_{d1}| = 1835.4 \text{ N}$$

$$P_{E1d2} = |Pr_{d2}| + |Ptr_{d2}| = 5625.7 \text{ N}$$

$$P_{E1d3} = |Pr_{d3}| + |Ptr_{d3}| = 4645.7 \text{ N}$$

$$P_{E1d4} = |Pr_{d4}| + |Ptr_{d4}| = 855.4 \text{ N}$$

$$Ptr_{d1} \text{ and } Ptr_{d4} = 0 \text{ N}$$

### Static Safety Factor

As indicated above, the maximum load is applied to the LM Guide during the leftward acceleration of the second LM block. Therefore, the static safety factor ( $f_s$ ) is obtained by the following equation.

$$f_s = \frac{C_0}{P_{E1a2}} = \frac{91.7 \times 10^3}{7958.9} = 11.5$$



**Average Load  $P_{m1}$** 

Obtain the average load applied to each LM block.

$$\begin{aligned}
 P_{m1} &= \sqrt[3]{\frac{1}{2 \cdot \ell_s} (P_{E1} a_1^3 \cdot S_1 + P_{E1}^3 \cdot S_2 + P_{E1} \ell d_1^3 \cdot S_3 + P_{E1} r a_1^3 \cdot S_1 + P_{E1}^3 \cdot S_2 + P_{E1} r d_1^3 \cdot S_3)} \\
 &= \sqrt[3]{\frac{1}{2 \times 1450} (0 \times 12.5 + 2891^3 \times 1400 + 4057.7^3 \times 37.5 + 6390.9^3 \times 12.5 + 2891^3 \times 1400 + 1835.4^3 \times 37.5)} \\
 &= 2939.5 \text{ N}
 \end{aligned}$$

$$\begin{aligned}
 P_{m2} &= \sqrt[3]{\frac{1}{2 \cdot \ell_s} (P_{E2} \ell a_2^3 \cdot S_1 + P_{E2}^3 \cdot S_2 + P_{E2} \ell d_2^3 \cdot S_3 + P_{E2} r a_2^3 \cdot S_1 + P_{E2}^3 \cdot S_2 + P_{E2} r d_2^3 \cdot S_3)} \\
 &= \sqrt[3]{\frac{1}{2 \times 1450} (7958.9^3 \times 12.5 + 4459^3 \times 1400 + 3403.4^3 \times 37.5 + 1292.4^3 \times 12.5 + 4459^3 \times 1400 + 5625.7^3 \times 37.5)} \\
 &= 4491.2 \text{ N}
 \end{aligned}$$

$$\begin{aligned}
 P_{m3} &= \sqrt[3]{\frac{1}{2 \cdot \ell_s} (P_{E3} \ell a_3^3 \cdot S_1 + P_{E3}^3 \cdot S_2 + P_{E3} \ell d_3^3 \cdot S_3 + P_{E3} r a_3^3 \cdot S_1 + P_{E3}^3 \cdot S_2 + P_{E3} r d_3^3 \cdot S_3)} \\
 &= \sqrt[3]{\frac{1}{2 \times 1450} (6978.9^3 \times 12.5 + 3479^3 \times 1400 + 2423.4^3 \times 37.5 + 312.4^3 \times 12.5 + 3479^3 \times 1400 + 4645.7^3 \times 37.5)} \\
 &= 3519.7 \text{ N}
 \end{aligned}$$

$$\begin{aligned}
 P_{m4} &= \sqrt[3]{\frac{1}{2 \cdot \ell_s} (P_{E4} \ell a_4^3 \cdot S_1 + P_{E4}^3 \cdot S_2 + P_{E4} \ell d_4^3 \cdot S_3 + P_{E4} r a_4^3 \cdot S_1 + P_{E4}^3 \cdot S_2 + P_{E4} r d_4^3 \cdot S_3)} \\
 &= \sqrt[3]{\frac{1}{2 \times 1450} (0 \times 12.5 + 1911^3 \times 1400 + 3077.7^3 \times 37.5 + 5410.9^3 \times 12.5 + 1911^3 \times 1400 + 855.4^3 \times 37.5)} \\
 &= 1983.7 \text{ N}
 \end{aligned}$$

**Nominal Life  $L_{10mn}$** 

The nominal life of the four LM blocks is obtained from the corresponding nominal life equations shown below.

$$L_{10m1} = \left( \alpha \times \frac{C}{P_{m1}} \right)^3 \times 50 = 160100 \text{ km}$$

$$L_{10m2} = \left( \alpha \times \frac{C}{P_{m2}} \right)^3 \times 50 = 44900 \text{ km}$$

$$L_{10m3} = \left( \alpha \times \frac{C}{P_{m3}} \right)^3 \times 50 = 93300 \text{ km}$$

$$L_{10m4} = \left( \alpha \times \frac{C}{P_{m4}} \right)^3 \times 50 = 521000 \text{ km}$$

$$\alpha = \frac{1}{f_w} \text{ (where } f_w = 1.5)$$

Therefore, the service life of the LM Guide used in a machine or equipment under the conditions stated above is equivalent to the nominal life of the second LM block, which is 44,900 km.

## Example of Calculating the Nominal Life (2) - with Vertical Mount

### Operating Conditions

Model No. : HSR25CA2SS+1500L- II  
 (basic dynamic load rating:  $C = 27.6 \text{ kN}$ )  
 (basic static load rating:  $C_0 = 36.4 \text{ kN}$ )

Mass	: $m_0 = 100 \text{ kg}$	Distance : $\ell_0 = 300 \text{ mm}$
	$m_1 = 200 \text{ kg}$	$\ell_1 = 80 \text{ mm}$
	$m__2 = 100 \text{ kg}$	$\ell_2 = 50 \text{ mm}$
Stroke	: $\ell_s = 1000 \text{ mm}$	$\ell_3 = 280 \text{ mm}$
		$\ell_4 = 150 \text{ mm}$
		$\ell_5 = 250 \text{ mm}$

The mass ( $m_0$ ) is loaded only during ascent; it is removed during descent.

Gravitational acceleration  $g = 9.8 \text{ (m/s}^2\text{)}$

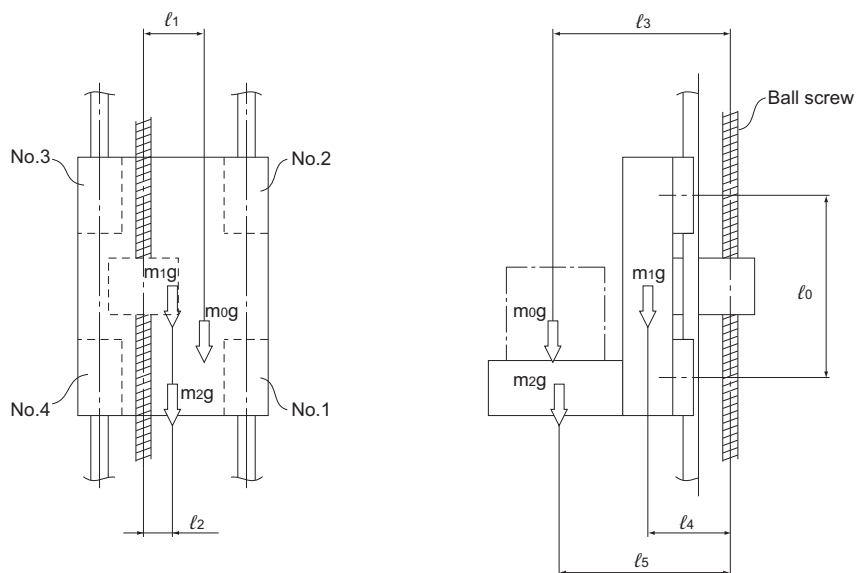


Fig. 13: Operating Conditions

## Load Applied to the LM Block

## ● During Ascent

■ Load applied to each LM block in the radial direction  $Pu_n$  during ascent

$$Pu_1 = + \frac{m_1 g \cdot \ell_4}{2 \cdot \ell_0} + \frac{m_2 g \cdot \ell_5}{2 \cdot \ell_0} + \frac{m_0 g \cdot \ell_3}{2 \cdot \ell_0} = + 1355.6 \text{ N}$$

$$Pu_2 = - \frac{m_1 g \cdot \ell_4}{2 \cdot \ell_0} - \frac{m_2 g \cdot \ell_5}{2 \cdot \ell_0} - \frac{m_0 g \cdot \ell_3}{2 \cdot \ell_0} = - 1355.6 \text{ N}$$

$$Pu_3 = - \frac{m_1 g \cdot \ell_4}{2 \cdot \ell_0} - \frac{m_2 g \cdot \ell_5}{2 \cdot \ell_0} - \frac{m_0 g \cdot \ell_3}{2 \cdot \ell_0} = - 1355.6 \text{ N}$$

$$Pu_4 = + \frac{m_1 g \cdot \ell_4}{2 \cdot \ell_0} + \frac{m_2 g \cdot \ell_5}{2 \cdot \ell_0} + \frac{m_0 g \cdot \ell_3}{2 \cdot \ell_0} = + 1355.6 \text{ N}$$

■ Load applied to each LM block in the lateral direction  $Ptu_n$  during ascent

$$Ptu_1 = + \frac{m_1 g \cdot \ell_2}{2 \cdot \ell_0} + \frac{m_2 g \cdot \ell_2}{2 \cdot \ell_0} + \frac{m_0 g \cdot \ell_1}{2 \cdot \ell_0} = + 375.7 \text{ N}$$

$$Ptu_2 = - \frac{m_1 g \cdot \ell_2}{2 \cdot \ell_0} - \frac{m_2 g \cdot \ell_2}{2 \cdot \ell_0} - \frac{m_0 g \cdot \ell_1}{2 \cdot \ell_0} = - 375.7 \text{ N}$$

$$Ptu_3 = - \frac{m_1 g \cdot \ell_2}{2 \cdot \ell_0} - \frac{m_2 g \cdot \ell_2}{2 \cdot \ell_0} - \frac{m_0 g \cdot \ell_1}{2 \cdot \ell_0} = - 375.7 \text{ N}$$

$$Ptu_4 = + \frac{m_1 g \cdot \ell_2}{2 \cdot \ell_0} + \frac{m_2 g \cdot \ell_2}{2 \cdot \ell_0} + \frac{m_0 g \cdot \ell_1}{2 \cdot \ell_0} = + 375.7 \text{ N}$$

## ● During Descent

■ Load applied to each LM block in the radial direction  $Pd_n$  during descent

$$Pd_1 = + \frac{m_1 g \cdot \ell_4}{2 \cdot \ell_0} + \frac{m_2 g \cdot \ell_5}{2 \cdot \ell_0} = + 898.3 \text{ N}$$

$$Pd_2 = - \frac{m_1 g \cdot \ell_4}{2 \cdot \ell_0} - \frac{m_2 g \cdot \ell_5}{2 \cdot \ell_0} = - 898.3 \text{ N}$$

$$Pd_3 = - \frac{m_1 g \cdot \ell_4}{2 \cdot \ell_0} - \frac{m_2 g \cdot \ell_5}{2 \cdot \ell_0} = - 898.3 \text{ N}$$

$$Pd_4 = + \frac{m_1 g \cdot \ell_4}{2 \cdot \ell_0} + \frac{m_2 g \cdot \ell_5}{2 \cdot \ell_0} = + 898.3 \text{ N}$$

■ Load applied to each LM block in the lateral direction  $Ptd_n$  during descent

$$Ptd_1 = + \frac{m_1 g \cdot \ell_2}{2 \cdot \ell_0} + \frac{m_2 g \cdot \ell_2}{2 \cdot \ell_0} = + 245 \text{ N}$$

$$Ptd_2 = - \frac{m_1 g \cdot \ell_2}{2 \cdot \ell_0} - \frac{m_2 g \cdot \ell_2}{2 \cdot \ell_0} = - 245 \text{ N}$$

$$Ptd_3 = - \frac{m_1 g \cdot \ell_2}{2 \cdot \ell_0} - \frac{m_2 g \cdot \ell_2}{2 \cdot \ell_0} = - 245 \text{ N}$$

$$Ptd_4 = + \frac{m_1 g \cdot \ell_2}{2 \cdot \ell_0} + \frac{m_2 g \cdot \ell_2}{2 \cdot \ell_0} = + 245 \text{ N}$$

### Combined Radial and Thrust Load

#### ● During Ascent

$$P_{Eu1} = |P_{u1}| + |P_{t_{u1}}| = 1731.3 \text{ N}$$

$$P_{Eu2} = |P_{u2}| + |P_{t_{u2}}| = 1731.3 \text{ N}$$

$$P_{Eu3} = |P_{u3}| + |P_{t_{u3}}| = 1731.3 \text{ N}$$

$$P_{Eu4} = |P_{u4}| + |P_{t_{u4}}| = 1731.3 \text{ N}$$

#### ● During Descent

$$P_{Ed1} = |P_{d1}| + |P_{t_{d1}}| = 1143.3 \text{ N}$$

$$P_{Ed2} = |P_{d2}| + |P_{t_{d2}}| = 1143.3 \text{ N}$$

$$P_{Ed3} = |P_{d3}| + |P_{t_{d3}}| = 1143.3 \text{ N}$$

$$P_{Ed4} = |P_{d4}| + |P_{t_{d4}}| = 1143.3 \text{ N}$$

### Static Safety Factor

The static safety factor ( $f_s$ ) of the LM Guide used in a machine or equipment under the conditions stated above is obtained as follows.

$$f_s = \frac{C_0}{P_{Eu2}} = \frac{36.4 \times 10^3}{1731.3} = 21.0$$

### Average Load $P_{mn}$

Obtain the average load applied to each LM block.

$$P_{m1} = \sqrt[3]{\frac{1}{2 \cdot \ell_s} (P_{Eu1}^3 \cdot \ell_s + P_{Ed1}^3 \cdot \ell_s)} = 1495.1 \text{ N}$$

$$P_{m2} = \sqrt[3]{\frac{1}{2 \cdot \ell_s} (P_{Eu2}^3 \cdot \ell_s + P_{Ed2}^3 \cdot \ell_s)} = 1495.1 \text{ N}$$

$$P_{m3} = \sqrt[3]{\frac{1}{2 \cdot \ell_s} (P_{Eu3}^3 \cdot \ell_s + P_{Ed3}^3 \cdot \ell_s)} = 1495.1 \text{ N}$$

$$P_{m4} = \sqrt[3]{\frac{1}{2 \cdot \ell_s} (P_{Eu4}^3 \cdot \ell_s + P_{Ed4}^3 \cdot \ell_s)} = 1495.1 \text{ N}$$

### Nominal Life $L_{10mn}$

The nominal life of the four LM blocks is obtained from the corresponding nominal life equations shown below.

$$L_{10m1} = \left( \alpha \times \frac{C}{P_{m1}} \right)^3 \times 50 = 182000 \text{ km}$$

$$L_{10m2} = \left( \alpha \times \frac{C}{P_{m2}} \right)^3 \times 50 = 182000 \text{ km}$$

$$L_{10m3} = \left( \alpha \times \frac{C}{P_{m3}} \right)^3 \times 50 = 182000 \text{ km}$$

$$L_{10m4} = \left( \alpha \times \frac{C}{P_{m4}} \right)^3 \times 50 = 182000 \text{ km}$$

$$\alpha = \frac{1}{f_W} \text{ (where } f_W = 1.2 \text{)}$$

Therefore, the service life of the LM Guide used in a machine or equipment under the conditions stated above is 182,000 km.